

# Issues in Safety Assurance

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# Summary

I want you to agree that:

- Safety Integrity Levels are harmful to safety and should be abandoned.
- We must urgently design a new basis for developing and assuring/certifying software-based safety systems.

# Safety-Related Systems

Computer-based safety-related systems (*safety systems*):

- sensors, actuators, control logic, protection logic, humans ...
- typically, perhaps, a few million transistors and some hundreds of kilobytes of program code and data. And some people.
- *Complex.*
- *Human error is affected by system design. The humans are part of the system.*

# Why systems fail: *some combination of ...*

- inadequate specifications
- hardware or software design error
- hardware component breakdown (*eg thermal stress*)
- deliberate or accidental external interference (*eg vandalism*)
- deliberate or accidental errors in fixed data (*eg wrong units*)
- accidental errors in variable data (*eg pilot error in selecting angle of descent, rather than rate*)
- deliberate errors in variable data (*eg spoofed movement authority*)
- human error (*eg shutting down the wrong engine*)
- ..... *others?*

# Safety Assurance

**Safety Assurance** should be about achieving *justified* confidence that the frequency of accidents will be acceptable.

- **Not** about satisfying standards or contracts
- **Not** about meeting specifications
- **Not** about subsystems

... but about whole systems and the probability that they will cause injury

So **ALL** these classes of failure are our responsibility.

# Failure and meeting specifications

A system **failure** occurs when the delivered service deviates from fulfilling the system **function**, the latter being what the system *is aimed at*. (J.C Laprie, 1995)

The phrase “what the system is aimed at” is a means of avoiding reference to a system “specification” - since it is not unusual for a system’s lack of dependability to be due to inadequacies in its documented specification.

(B Randell, Turing Lecture 2000)

# The scope of a safety system:

*The developers of a safety system should be accountable for **all possible failures** of the physical system it controls or protects, **other than those explicitly excluded** by the agreed specification.*

# Estimating failure probability

## from various causes

- ✘ Inadequate specifications
- ✘ hardware or software design error
- ✓ hardware component breakdown (*component data*)
- ✘ deliberate or accidental external interference
- ✘ deliberate or accidental errors in fixed data
- ✓ accidental errors in variable data/human error (*HCI testing and psychological data*)
- ✘ deliberate errors in variable data
- ➔ *System failure probabilities cannot usually be determined from consideration of these factors.*



# Assessing whole systems

In principle, a system can be monitored under typical operational conditions for long enough to determine *any* required probability of unsafe failure, from any cause, with *any* required level of confidence.

*In practice, this is rarely attempted. Even heroic amounts of testing are unlikely to demonstrate better than  $10^{-4}$ /hr at 99%.*

So what are we doing requiring  $10^{-8}$ /hr (and claiming to have evidence that it has been achieved?).

I believe that we need to stop requiring/making such claims.

... so let's look at SILs

# Safety Integrity Levels

Low Demand:  $< 1/\text{yr}$  AND  $< 2^*$  proof-test freq.

Safety integrity level	Low demand mode of operation (Average probability of failure to perform its design function on demand)
4	$\geq 10^{-5}$ to $< 10^{-4}$
3	$\geq 10^{-4}$ to $< 10^{-3}$
2	$\geq 10^{-3}$ to $< 10^{-2}$
1	$\geq 10^{-2}$ to $< 10^{-1}$

Proof testing is generally infeasible for software functions.

IEC  
61508

Why should a rarely-used function, frequently re-tested exhaustively, and only needing  $10^{-5}$  pfd, have the same SIL as a constantly challenged, never tested exhaustively,  $10^{-9}$  pfh function? *Low demand mode should be dropped for software.*

# Safety Integrity Levels

## High demand

Safety integrity level	High demand or continuous mode of operation (Probability of a dangerous failure per hour)
4	$\geq 10^{-9}$ to $< 10^{-8}$
3	$\geq 10^{-8}$ to $< 10^{-7}$
2	$\geq 10^{-7}$ to $< 10^{-6}$
1	$\geq 10^{-6}$ to $< 10^{-5}$

Even SIL 1 is beyond reasonable assurance by testing.

IEC  
61508

IEC 61508 recognises the difficulties for assurance, but has chosen to work within current approaches by regulators and industry.

*What sense does it make to attempt to distinguish single factors of 10 in this way? Do we really know **so much** about the effect of different development methods on product failure rates?*

SafeComp 2003

# How do SILs affect software?

- SILs are used to recommend software development (including assurance) methods
  - stronger methods more highly recommended at higher SILs than at lower SILs
- This implies
  - the recommended methods lead to fewer failures
  - their cost cannot be justified at lower SILs

Are these assumptions true?

# (1) SILs and code anomalies

(source: German & Mooney, Proc 9th SCS Symposium, Bristol 2001)

- Static analysis of avionics code:
  - software developed to levels A or B of DO-178b
  - software written in C, Lucol, Ada and SPARK
  - residual anomaly rates ranged from
    - 1 defect in 6 to 60 lines of C
    - 1 defect in 250 lines of SPARK
  - 1% of anomalies judged to have safety implications
  - **no significant difference between levels A & B.**
- *Higher SIL practices did not affect the defect rates.*

## Safety anomalies found by static analysis in DO 178B level A/B code:

- Erroneous signal de-activation.
- Data not sent or lost
- Inadequate defensive programming with respect to untrusted input data
- Warnings not sent
- Display of misleading data
- Stale values inconsistently treated
- Undefined array, local data and output parameters

- Incorrect data message formats
- Ambiguous variable process update
- Incorrect initialisation of variables
- Inadequate RAM test
- Indefinite timeouts after test failure
- RAM corruption
- Timing issues - systems runs backwards
- Process does not disengage when required
- Switches not operated when required
- System does not close down after failure
- Safety check not conducted within a suitable time frame
- Use of exception handling and continuous resets
- Invalid aircraft transition states used
- Incorrect aircraft direction data
- Incorrect Magic numbers used
- Reliance on a single bit to prevent erroneous operation

Source: Andy German,  
Qinetiq. Personal  
communication.

## (2) Does strong software engineering cost more?

- Dijkstra's observation: avoiding errors makes software cheaper. (Turing Award lecture, 1972)
- Several projects have shown that very much lower defect rates can be achieved alongside cost savings.
  - (see <http://www.sparkada.com/industrial>)
- *Strong methods do not have to be reserved for higher SILs*



# SILs: Conclusions

- SILs are unhelpful to software developers:
  - SIL 1 target failure rates are already beyond practical verification.
  - SILs 1-4 subdivide a problem space where little distinction is sensible between development and assurance methods.
  - There is little evidence that many recommended methods reduce failure rates
  - There is evidence that the methods that *do* reduce defect rates also save money: *they should be used at any SIL.*

## SILs: Conclusions (2)

- SILs set developers impossible targets
  - so the focus shifts from achieving adequate safety to meeting the recommendations of the standard.
  - this is a shift from *product* properties to *process* properties.
  - but there is little correlation between process properties and safety!
- So SILs actually damage safety.

# A pragmatic approach to safety

- Revise upwards target failure probabilities
  - current targets are rarely achieved (it seems)  
but most failures do not cause accidents
  - ... so current pfh targets are unnecessarily low
  - safety cases are damaged because they have to claim probabilities for which no adequate evidence can exist - so engineers aim at satisfying standards instead of improving safety
- We should press for current targets to be reassessed.

## A pragmatic approach to safety (2)

- Require that *every* safety system has a formal specification
  - this inexpensive step has been shown to resolve many ambiguities
- Abandon SILs
  - the whole idea of SILs is based on the false assumption that stronger development methods cost more to deploy. Define a core set of system properties that must be demonstrated for all safety systems.

## A pragmatic approach to safety (3)

- Require the use of a programming language that has a formal definition and a static analysis toolset.
  - A computer program is a mathematically formal object. It is essential that it has a single, defined meaning and that the absence of major classes of defects has been demonstrated.

## A pragmatic approach to safety (4)

- Safety cases should start from the position that *the only acceptable evidence* that a system meets a safety requirement is an independently reviewed proof or statistically valid testing.
  - Any compromise from this position should be explicit, and agreed with major stakeholders.
  - This agreement should explicitly allocate liability if there is a resultant accident.

## A pragmatic approach to safety (5)

- If early operational use provides evidence that contradicts assumptions in the safety case (for example, if the rate of demands on a protection system is much higher than expected), the system should be withdrawn and re-assessed before being recommissioned.
  - This threat keeps safety-case writers honest.

## A pragmatic approach to safety (6)

- Where a system is modified, its whole safety assessment must be repeated *except* to the extent that it can be proved to be unnecessary.
  - Maintenance is likely to be a serious vulnerability in many systems currently in use.



## A pragmatic approach to safety (6)

- COTS components should conform to the above principles
  - Where COTS components are selected *without* a formal proof or statistical evidence that they meet the safety requirements in their new operational environment, the organisation that selected the component should have strict liability for any consequent accident.
  - “proven in use” should be withdrawn.

## A pragmatic approach to safety (7)

- All safety systems should be warranted free of defects by the developers.
  - The developers need to “keep some skin in the game”
- Any safety system that could affect the public should have its development and operational history maintained in escrow, for access by independent accident investigators.

# Safety and the Law

- In the UK, the Health & Safety at Work Act's ALARP principle creates a legal obligation to reduce risks as low as reasonably practicable.
- Court definition of *reasonably practicable*: “the cost of undertaking the action is not grossly disproportionate to the benefit gained.”
- In my opinion, my proposals *would reduce risks* below current levels and *are reasonably practicable*. Are they therefore legally required?

# Summary

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- We must urgently design a new basis for developing and assuring/certifying software-based safety systems.

Do you agree?